



INSTITUTE FOR SYSTEMS AND ROBOTICS



## *Annual Report – 2012*

### *Lisbon Pole*

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## **1. EXECUTIVE SUMMARY**

During the year of 2012 there were no research and technological activities taking place in the framework of the Lisbon Pole of ISR, nor were financed through ISR (NIF 502 854 227). All the research activities were carried out in the context of the research unit ISR/IST where all contracts and activities took place at Instituto Superior Técnico.

For informative purposes only, we describe the scientific publications and Theses that were produced by the research group hosted at the Instituto Superior Técnico, inspite of the fact that none of these activities were developed in the context of the Lisbon Pole of ISR.

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## 2. PUBLICATIONS

### a) Ph.D. Theses (4)

1. **AbdolkarimPahliani**, Active Cooperative Perception in Networked Robot Systems, Ph.D. Thesis, Instituto Superior Técnico, Universidade Técnica de Lisboa, March, 2012.
2. **Paulo Santos**, Ocean Parameter Estimation with High-Frequency signals using a Vector Sensor Array, Ph.D. Thesis, University of Algarve, Portugal, November, 2012.
3. **DariaMigotina**, Symbolic Representation of the Sleep Electroencephalogram Application in the Analysis of Sleep”, Ph.D. Thesis, Instituto Superior Técnico, Lisbon, Portugal, June 2012.
4. **VahidHassani**, Multiple Model Robust Adaptive Estimation and Control, Ph.D. Thesis, Instituto Superior Técnico, Universidade Técnica de Lisboa, December, 2012.

### b) M.Sc. Theses (32)

1. **Pedro Lourenço**, Analysis, Design and Implementation of an Integrated Simultaneous Localization and Mapping Algorithm, Master Thesis, Instituto Superior Técnico, Universidade Técnica de Lisboa, 2012
2. **João Leal**, Adaptive ROC analysis in Carotid Atherosclerosis Diagnosis for Endarterectomy, Master Thesis, Instituto Superior Técnico, Universidade Técnica de Lisboa, 2012
3. **Marta Sousa**, Classification in dementia based on structural and perfusion MRI, Master Thesis, Instituto Superior Técnico, Universidade Técnica de Lisboa, 2012
4. **Ana Afonso**, Classification of Pigmented Skin Lesions based on Color Features, Master Thesis, Instituto Superior Técnico, Universidade Técnica de Lisboa, 2012
5. **João Semedo**, Model-Based Clustering Applied to Sleep Macrostructure Analysis, Master Thesis, Instituto Superior Técnico, Universidade Técnica de Lisboa, 2012
6. **Mariana Francisco**, Sobre o Papel da Textura na Detecção Automática de Melanomas, Master Thesis, Instituto Superior Técnico, Universidade Técnica de Lisboa, 2012
7. **Joana Pinto**, Spatiotemporal dynamics of CBF and BOLD fMRI responses to breath-hold challenges, Master Thesis, Instituto Superior Técnico, Universidade Técnica de Lisboa, 2012
8. **Ana Ruela**, What is the role of color in dermoscopy analysis?, Master Thesis, Instituto Superior Técnico, Universidade Técnica de Lisboa, 2012
9. **Bruno Ribeiro**, A Robotic player of Six Men's Morris with a redundant Manipulator, Master Thesis, Instituto Superior Técnico, Universidade Técnica de Lisboa, 2012
10. **Davide Periquito**, Architecture for Augmented Reality interface, Master Thesis, Instituto Superior Técnico, Universidade Técnica de Lisboa, 2012

11. **João Carvalho**, Assisted Teleoperation of Quadcopters Using Obstacle Avoidance, Master Thesis, Instituto Superior Técnico, Universidade Técnica de Lisboa, 2012
12. **Pedro Morgado**, Automated Diagnosis of Alzheimer's Disease using PET Images - A study of alternative procedures for feature extraction and selection, Master Thesis, Instituto Superior Técnico, Universidade Técnica de Lisboa, 2012
13. **Gonçalo Deus**, Automação de um Sistema de Respirometria, Master Thesis, Instituto Superior Técnico, Universidade Técnica de Lisboa, 2012
14. **Duarte Dias**, Barcode-based Localization of Low Capacity Mobile Robots in Structured Environments, Master Thesis, Instituto Superior Técnico, Universidade Técnica de Lisboa, 2012
15. **Tiago Marcelo**, Control of An Autonomous Motorbike, Master Thesis, Instituto Superior Técnico, Universidade Técnica de Lisboa, 2012
16. **Henrique Silva**, Controlo de Formações em Veículos Aéreos não Tripulados, Master Thesis, Instituto Superior Técnico, Universidade Técnica de Lisboa, 2012
17. **Maria Féria**, Decision and Control System of a solar Powered Train, Master Thesis, Instituto Superior Técnico, Universidade Técnica de Lisboa, 2012
18. **Ana Alarza**, Detecting Conversion of Mild Cognitive Impairment to Alzheimer, Master Thesis, Instituto Superior Técnico, Universidade Técnica de Lisboa, 2012
19. **Sérgio Copeto**, Detecção de Objectos Activos em Ambientes Dinâmicos, Master Thesis, Instituto Superior Técnico, Universidade Técnica de Lisboa, 2012.
20. **Marta Calero**, Diagnosis of Alzheimer's Disease and Mild Cognitive Impairment Exploiting Class Ordering, Master Thesis, Instituto Superior Técnico, Universidade Técnica de Lisboa, 2012.
21. **João Reis**, Immersive Robot Teleoperation Using an Hybrid Virtual and Real Stereo Camera Attitude Control, Master Thesis, Instituto Superior Técnico, Universidade Técnica de Lisboa, 2012.
22. **João Cóias**, Attitude Determination Using Multiple L1 GPS Receivers, Master Thesis, Instituto Superior Técnico, Universidade Técnica de Lisboa, 2012.
23. **Valter Roldão**,Formation Control of Autonomous Air Vehicles, Master Thesis, Instituto Superior Técnico, Universidade Técnica de Lisboa, 2012.
24. **José Sousa**, Target Localization and Mapping from an Aerial Vehicle, Master Thesis, Instituto Superior Técnico, Universidade Técnica de Lisboa, 2012.
25. **Fábio Gameiro**, Implementação e monitorização de uma rede de sensores móveis para medição da qualidade do ar, Master Thesis, Instituto Superior Técnico, Universidade Técnica de Lisboa, 2012.
26. **Pedro Vieira**, Interactive Mapping Using Range Sensor Data under Localization Uncertainty, Master Thesis, Instituto Superior Técnico, Universidade Técnica de Lisboa, 2012.
27. **João Fonseca**, Montagem Automática de Painéis de Azulejos, Master Thesis, Instituto Superior Técnico, Universidade Técnica de Lisboa, 2012.

28. **Manuel Silva**, Network Cameras Calibration, Master Thesis, Instituto Superior Técnico, Universidade Técnica de Lisboa, 2012.
29. **Filipe Veiga**, Robotic Grasp Optimization from Contact Force Analysis, Master Thesis, Instituto Superior Técnico, Universidade Técnica de Lisboa, 2012.
30. **Pedro Varela**, Sentiment Analysis, Master Thesis, Instituto Superior Técnico, Universidade Técnica de Lisboa, 2012.
31. **Filipe Jesus**, Simultaneous Localization and Mapping Using Vision for Search and Rescue Robots, Master Thesis, Instituto Superior Técnico, Universidade Técnica de Lisboa, 2012.
32. **Rui Figueiredo**, Simultaneous Recognition and Pose Estimation of Multiple 3D Objects: Real-Time Probabilistic Methods using Kinect Data, Master Thesis, Instituto Superior Técnico, Universidade Técnica de Lisboa, 2012.

### **c) In Books (9)**

1. D. Milutinovic, Pedro Lima, Biological Cell Inspired Stochastic Models and Control, in Microbiorobotics - Biologically Inspired Microscale Robotic Systems, MinJun Kim, A. Agung Julius, Edward Steager (Eds), Elsevier Micro & Nano Technologies Series, 2012.
2. Matthijs T. J. Spaan, Partially Observable Markov Decision Processes, In Marco Wiering and Martijn van Otterlo, editors, Reinforcement Learning: State of the Art, pp. 387–414, Springer Verlag, 2012.
3. Barriga, F.J.A.S., J.M.R.S. Relvas, R.S. Santos & A. Pascoal 2012. Ciência e Recursos Minerais na Última Frontera. Pp. 121-132. In: João Guerreiro (Ed.) Mar Português: Conhecimento, Valorização e Desenvolvimento. Universidade do Algarve. 236pp. [ISBN 978-989-8472-27-4], 2012.
4. J. S. Marques, J. C. Nascimento, C. Santiago, Robust Deformable Models for 2D and 3D Shape Estimation, in Deformation Models, M. González, A. Mir, J. Varona, eds., chapter, Springer, LNCVB-7, 2012.
5. Kurosh Madani, António Dourado Correia, Agostinho Rosa And Joaquim Filipe (eds.). (2012) Computational Intelligence, Springer, Series: Studies In Computational Intelligence, Volume 399, 2012. DOI: 10.1007/978-3-642-27534-0
6. Chin Ian Low, Daria Migotina, Joao P Rodrigues, Joao Semedo, Feng Wan, Peng Un Mak, Mang I Vai, Fernando Melicio, J Gomes Pereira and Agostinho Rosa. Object Recognition Test in Peripheral Vision: A Study on the Influence of Object Color, Pattern and Shape. Lecture Notes in Computer Science 7670 pp 18-26, Springer 2012, ISBN 978-3-642-35138-9.
7. C.M. Fernandes, J.J. Merelo, A.C. Rosa. (2012). Enhancing the Adaptive Dissortative Mating Genetic Algorithm in Fast Non Stationary Fitness Functions. Studies in Computational Intelligence, Springer, Volume 399, pp 115-130, 2012.
8. C.M. Fernandes, J.J. Merelo, A.C. Rosa. Controlling the Parameters of the Particle Swarm Optimization with a Self-Organized Criticality. 12<sup>th</sup> International Conference on Parallel Problem Solving from Nature, Lecture Notes in Computer Science Volume 7492, 2012, pp. 153-163, 2012.

9. A. Pedro Aguiar and António Pascoal, Cooperative Control of Multiple Autonomous Marine Vehicles: Theoretical Foundations and Practical Issues, in Recent Advances in Unmanned Vehicles, IET, Editors Geoff Roberts and Robert Sutton, 2012.

#### d) In International Journals (45)

1. J. Ruesch, R. Ferreira, A. Bernardino, Predicting visual stimuli from self-induced actions: an adaptive model of a corollary discharge circuit, *IEEE Transactions on Autonomous Mental Development* 2012.
2. Nicola Greggio, Alexandre Bernardino, Cecilia Laschi, Paolo Dario, José Santos-Victor, Fast estimation of Gaussian mixture models for image segmentation, in *Mach. Vis. Appl.* 23(4): 773-789 (2012).
3. Giampiero Salvi, Luis Montesano, Alexandre Bernardino, José Santos-Victor, Language Bootstrapping: Learning Word Meanings From Perception-Action Association, in *IEEE Transactions on Systems, Man, and Cybernetics, Part B* 42(3): 660-671, 2012.
4. P. Ribeiro, P. Moreno, J. Santos-Victor, Introducing fuzzy decision stumps in boosting through the notion of neighbourhood, *IET Computer vision* 6(3), 2012.
5. Hugo Costelha, Pedro Lima, Robot task plan representation by Petri nets: modelling, identification, analysis and execution, *Autonomous Robots*, Volume 33, Issue 4, pp 337-360, November 2012.
6. P. Lichocki, Danesh Tarapore, L. Keller, D. Floreano, Neural networks as mechanisms to regulate division of labor, *The American Naturalist*, vol. 179, no. 3, pp. 391-400, 2012.
7. L. Merino, A. Gilbert, Jesús Capitán, R. Bowden, J. Illingworth, A. Ollero, Data Fusion in Ubiquitous Networked Robot Systems for Urban Services, *Annals of Telecommunications*, special issue on Ubiquitous Networked Robots, Vol. 67, No. 7-8, 2012.
8. Rajneesh Sharma and Matthijs T. J. Spaan, PuBayesian Game Based Fuzzy Reinforcement Learning Control for Decentralized POMDPs, *IEEE Transactions on Computational Intelligence and AI in Games*, 4(4):309–328, 2012.
9. Jorge JP, Figueiredo P, van der Zwaag W, Marques JP, Signal fluctuations in fMRI data acquired with 2D-EPI and 3D-EPI at 7 Tesla. *Magn. Reson. Imag.*, 2012 [Epub ahead of print]
10. Murta T, Leal A, Garrido M, Figueiredo P, Dynamic Causal Modelling of epileptic seizure propagation pathways: a combined EEG-fMRI study. *NeuroImage* 62(3): 1634-1642, 2012.
11. Lemos R, Figueiredo P, Santana I, Simões MR, Castelo-Branco M, Temporal integration of 3D coherent motion cues defining simple objects of unknown orientation is impaired in amnestic Mild Cognitive Impairment and Alzheimer's Disease. *Journal of Alzheimer's Disease* 28(4):885-96, 2012.
12. Khovanov, M., A. Lauda, M. A. Mackaay, and M. Stosic (2012). Extended graphical calculus for categorified quantum  $sl(2)$ . *Mem. Amer. Math. Soc.* 219 (1029). arXiv:1006.2866, 2012.
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14. Rodrigues, J.M.F., Lam, R., du Buf, J.M.H., Cortical 3D Face and Object Recognition Using 2D Projections, *International Journal of Creative Interfaces and Computer Graphics*, Vol. 3, No 1, pp. 45-6, 2012.

15. Serrão, M., Rodrigues, J.M.F., Rodrigues, J.I. and du Buf, J.M.H, Indoor localization and navigation for blind persons using visual landmarks and a GIS, *Procedia Computer Science*, Vol. 14, pp. 65 – 73. doi: 10.1016/j.procs.2012.10.008, 2012.
16. Moreno, M., Shahrabadi, S., José, J., du Buf, J.M.H. and Rodrigues, J.M.F., Realtime local navigation for the blind: detection of lateral doors and sound interface, *Procedia Computer Science* Vol. 14, pp. 74 – 82, 2012.
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32. Férnandez-Ares, A.M. Mora, J.J. Merelo, P. García-Sánchez, C.M. Fernandes, "Effect of Noisy Fitness in Real-Time Strategy Games Player BehaviourOptimisation Using Evolutionary Algorithms", *Journal of Computer Science and Technology*, Journal of Computer Science and Technology, 27(5), pp. 1007-1023, 2012.
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35. Bruno Guerreiro, Carlos Silvestre, and Rita Cunha, Terrain Avoidance Nonlinear Model Predictive Control for Autonomous Rotorcraft, *Journal of Intelligent & Robotic Systems*, Volume 68, Issue 1, pages: 69-85, September 2012.
36. L. P. Perera, C. GuedesSoares, and Paulo Oliveira, Maritime Traffic Monitoring Based on Vessel Detection, Tracking, State Estimation, and Trajectory Prediction, *Transactions on Intelligent Transportation Systems*, IEEE, vol. 13, nº 3, pp. 1188-1200, September 2012.
37. Pedro Batista, Carlos Silvestre, and Paulo Oliveira, Sensor-based Globally Asymptotically Stable Filters for Attitude Estimation: Analysis, Design, and Performance Evaluation, *IEEE Transactions on Automatic Control*, Volume 57, Issue 8, Pages: 2095 – 2100, August 2012.
38. João Almeida, Carlos Silvestre, and AntónioPascoal, Continuous-time consensus with discrete-time communications, *Elsevier Systems and Control Letters*, Volume 61, Issue 7, Pages: 788-796, July 2012.
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42. João Almeida, Carlos Silvestre, and AntónioPascoal, Cooperative control of multiple surface vessels with discrete-time periodic communications, *International Journal of Robust and Nonlinear Control*, Volume 22, Pages: 398–419, Pages: 398–419, March 2012.

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### **e) In International Conferences (184)**

1. M. Silva, R. Ferreira, J. Gaspar, Camera Calibration using a Color-Depth Camera: Points and Lines Based DLT including Radial Distortion, In WS in Color-Depth Camera Fusion in Robotics, held with IROS 2012, October 7, 2012, Vilamoura, Portugal.
2. Nuno Moutinho, Martim Brandão, Ricardo Ferreira, José Gaspar, Alexandre Bernardino, Atsuo Takanishi, José Santos-Victor, Online Calibration of a Humanoid Robot Head from Relative Encoders, IMU Readings and Visual Data, IROS 2012.
3. Ricardo Galego, Alexandre Bernardino, José Gaspar, Auto-calibration of Pan-Tilt Cameras including Radial Distortion and Zoom, International Symposium on Visual Computing (ISVC), July 16-18, Crete, Greece, 2012.
4. R. de Souza, A. Bernardino, J. Santos-Victor, A. Billard, On the Representation of Anthropomorphic Robot Hands: Shape versus Function, HUMANOIDS 2012.
5. R. Figueiredo, A. Shukla, D. Aragão, P. Moreno, A. Bernardino, J. Santos-Victor, A. Billard, Reaching and Grasping Kitchenware Objects, In SII 2012.
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8. U. Prieur, V. Perdereau, A. Bernardino, Modeling and Planning High\*-Level In\*-Hand Manipulation Actions from Human Knowledge and Active Learning from Demonstration, In IROS 2012, Vilamoura, Portugal.
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11. Bogdan Moldovan, Plinio Moreno, Martijn van Otterlo, José Santos-Victor, Luc De Raedt, Learning relational affordance models for robots in multi-object manipulation tasks, in ICRA 2012: 4373-4378.
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21. Jesús Capitán, Matthijs Spaan, L. Merino, Role-based Cooperation for Environmental Monitoring with Multiple UAVs, IROS Workshop on Robotics for Environmental Monitoring, Vilamoura, Portugal, 2012.
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30. Pedro Vieira, Rodrigo Ventura, Interactive Mapping using Range Rensor Data Under Localization Uncertainty, Proc. of PEMRA 2012 - 1st International Workshop on Perception for Mobile Robots Autonomy, Poznan, Poland, 2012.
31. Pedro Vieira, Rodrigo Ventura, Interactive 3D Scan-Matching Using RGB-D Data, Proc. of ETFA - 17th IEEE International Conference on Emerging Technologies & Factory Automation, Kraków, Poland, 2012.
32. Alberto Vale, F. Valente, M. Isabel Ribeiro, J. Ferreira, Rodrigo Ventura, Motion planning and localization approaches for mobile robot navigation in ITER, Proc. of Robotica 2012, Guimarães, Portugal. pp. 75-80, 2012.
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