



**INSTITUTE FOR SYSTEMS AND ROBOTICS**



## ***Annual Report – 2016***

### ***Lisbon Pole***

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## 1. EXECUTIVE SUMMARY

During the year of 2016 there were no research and technological activities taking place in the framework of the Lisbon Pole of ISR, nor were financed through ISR (NIF 502 854 227). All the research activities were carried out in the context of the research unit ISR/IST where all contracts and activities took place at Instituto Superior Técnico.

For informative purposes only, we describe the scientific publications and doctoral theses that were produced by the research group hosted at the Instituto Superior Técnico, in spite of the fact that none of these activities were developed in the context the Lisbon Pole of ISR.

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## 2. PUBLICATIONS

### A. International Journals,

- [1] Pedro Serra, Rita Cunha, Tarek Hamel, David Cabecinhas, Carlos Silvestre, Landing of a Quadrotor on a Moving Target using Dynamic Image-Based Visual Servo Control, *IEEE Transactions on Robotics*, Volume 32, Issue 6, Pages 1524- 1535, December 2016
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- [4] M. Farrajota, João Rodrigues, Hans Du Buf, Using Multi-Stage Features in Fast R-CNN for Pedestrian Detection, Proc. of DSAI 2016 - Software Development and Technologies for Enhancing Accessibility and Fighting Info-exclusion, UTAD, Vila Real, Portugal, 2016
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- [12] Carlos Santiago, Jacinto Nascimento, Jorge S. Marques, Segmentation of the Left Ventricle in Cardiac MRI using a Robust Active Shape Model Approach, Proc. of RecPad 2016 - 22nd edition of the Portuguese Conference on Pattern Recognition, Aveiro, Portugal, 2016 - PDF
- [13] David Moreno-Salinas, N. Crasta, Miguel Ribero, M. Bayat, A. M. Pascoal, and J. A. Aranda, "Integrated motion planning, control, and estimation for range-based marine vehicle positioning and target localization," Proc. 10th IFAC Conference on Control Applications in Marine Systems (CAMS' 2016), Trondheim, Norway, 2016.
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